Documentation – Device Integration Dragar VN800

Digital Health
CONNECTING BEST CARE

Digital Health
Quick Reference Guide

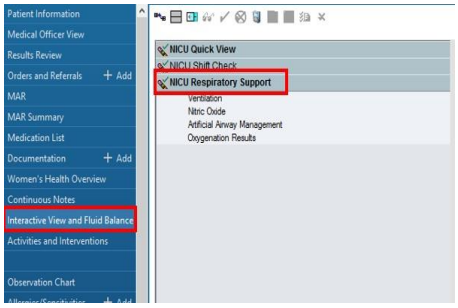
This Quick Reference Guide will explain how to:

Complete documentation for the Dragar VN800 that has device integration active

This QRG is written with the assumption that Device association has already occurred. Please refer to the BMDI Device association, documentation and disassociation QRG for this process.

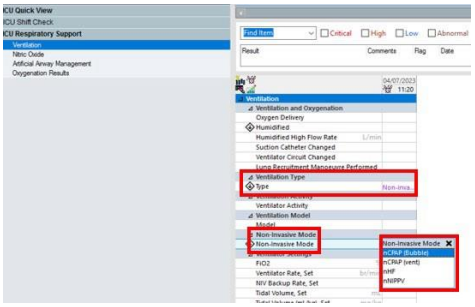
Documentation of Non-Invasive Ventilation

1. From **Interactive View** (iView) > **NICU Respiratory Support band**



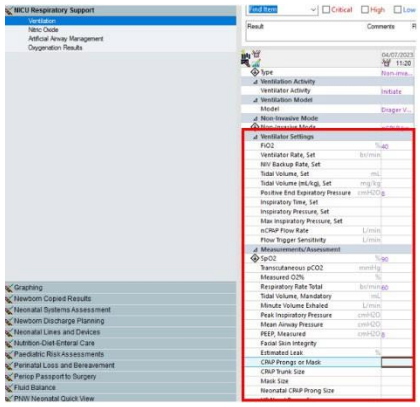
2. Select **Ventilation** > **Ventilation Type** > **Non-Invasive**
   This will open conditional logic to enable documentation of non-invasive modes

   Note: only modes that are delivered via the Dragar VN800 will come through with device association. All other modes/devices will require manual documentation



3. Double click on the **Ventilator Settings** and **Measurements/Assessments** headers to pull through values. Review the values, validate and then save via the **Green** tick.

   Note: data regarding interface choice, size, nasal skin integrity will not pull from the ventilator. This will be manual documentation.

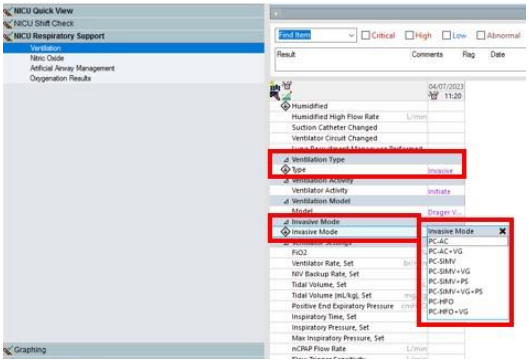


Documentation of Invasive Ventilation

1. Select **Invasive Mode** under the Ventilation Type heading
   This will open conditional logic to be able to select the correct mode.

   Documentation of data points is the same process for non-invasive modes as above.

   Note: In order to see the HFOV data points, the mode of HFOV or HFOV +VG needs to be selected.



Important – Call out box heading in this size, font and colour

- Documentation of ventilation type, activity, mode, device model, interface information and NIV back up rate will be manual documentation.
- Make sure to validate all values prior to saving to ensure accurate reflection of patient condition.
- All values can be overwritten if needed

Handy Hint – Call out box heading in this size, font and colour

For data points under conditional logic – i.e. HFOV, once you have saved this data once, the data points will remain on view for future documentation.